

# ODE Assignment II

To present Sunday, June 5

1. Logan p. 158 #15; 2. Logan p. 163 #10

Problem 1 Logan p. 158 #15

Solve — by both the patching method and by the Laplace transform method — the initial value problem

$$x'' + \pi^2 x = \begin{cases} \pi^2, & 0 < t < 1 \\ 0, & t > 1 \end{cases}$$

where  $x(0) = 1$  and  $x'(0) = 0$ .

I am going to call  $\pi$  "w" and change the problem to

$$x'' + \omega^2 x = \begin{cases} \omega^2, & 0 < t < \frac{\pi}{\omega} \\ 0, & t > \frac{\pi}{\omega} \end{cases}$$

It is of course the same problem if you stick in  $\omega = \pi$ .

## Problem 1 (CONT'D)

Solution by patching method.  
From 0 to  $\frac{\pi}{\omega}$  we have

$$x'' + \omega^2 x = \omega^2$$

We need a particular solution of the homogeneous equation. I can just see it: it is  $x_p(t) = 1$ . Also, that solution satisfies  $x(0) = 1$  and  $x'_p(0) = 0$ , so we don't have to add in any of the homogeneous sol'n.  
At  $t = \frac{\pi}{\omega}$ , the forcing function is suddenly removed. The system will now oscillate with some combination of

$$c_1 \cos \omega t + c_2 \sin \omega t$$

For this period, the initial condition is

$$x\left(\frac{\pi}{\omega}\right) = 1 \quad \text{and} \quad x'\left(\frac{\pi}{\omega}\right) = 0$$

Plugging  $\frac{\pi}{\omega}$  in for  $t$ , we have

$$c_1 \underbrace{\cos \omega \frac{\pi}{\omega}} + c_2 \underbrace{\sin \omega \frac{\pi}{\omega}} = c_1 = 1$$

Doing the same thing with the first derivative, we have

$$-c_1 \omega \underbrace{\sin \omega \frac{\pi}{\omega}} + c_2 \omega \underbrace{\cos \omega \frac{\pi}{\omega}} = -c_2 = 0$$

So we are done and can summarize

$$x(t) = \begin{cases} 1 & 0 \leq t \leq \frac{\pi}{\omega} \\ -\cos \omega t & \frac{\pi}{\omega} < t \end{cases}$$

## Problem 1 (cont'd)

Solution by Laplace transform method.  
We rewrite the problem using the Heaviside function.

$$x'' + \omega^2 x = \omega^2 - \omega^2 H\left(t - \frac{\pi}{\omega}\right)$$

We Laplace transform the equation

$$\begin{aligned} s^2 X(s) - s x(0) - x'(0) + \omega^2 X(s) \\ = \omega^2 \frac{1}{s} \left(1 - e^{-\frac{\pi}{\omega} s}\right) \end{aligned}$$

$$\text{So } X(s) = \frac{1}{s^2 + \omega^2} \left[ \underbrace{s}_{\text{1st term}} + \underbrace{\frac{\omega^2}{s}}_{\text{2nd term}} \left( \underbrace{1}_{\text{3rd term}} - e^{-\frac{\pi}{\omega} s} \right) \right]$$

Consulting the table on p. 175, the first term is  $\cos \omega t$ . The second term is the product of  $\frac{1}{s^2 + \omega^2}$  and  $\frac{\omega^2}{s}$ .  $\frac{1}{s^2 + \omega^2}$  is  $\frac{1}{\omega} \sin \omega t$ .

$\frac{\omega^2}{s}$  is  $\omega^2 H(t)$ . The product rule near the bottom of p. 175, tells us

$$\int_0^t \frac{1}{\omega} \sin \omega \tau \cdot \omega^2 \overbrace{H(t-\tau)}^{\text{Heaviside}} d\tau = -\cos \omega t + 1$$

## Problem 1 (CONT'D)

So the 1st and 2nd terms together have just given us 1. The 3rd term is  $-e^{-\frac{\pi}{\omega} s}$  times the second term. The second term gave us

$$-\cos \omega t + 1$$

The third term therefore gives us

$$\begin{aligned} & -H\left(t - \frac{\pi}{\omega}\right) \left[ -\cos \omega \left(t + \frac{\pi}{\omega}\right) + 1 \right] \\ & = H\left(t - \frac{\pi}{\omega}\right) \left[ -\cos \omega t - 1 \right] \end{aligned}$$

To summarize  $\leftarrow$  from 1st and 2nd terms  $\leftarrow$  from 3rd term

$$x(t) = 1 + H\left(t - \frac{\pi}{\omega}\right) \left[ -\cos \omega t - 1 \right]$$

This is in perfect agreement with the patching method.

Problem 2 Logan p. 163 #10

Write an integral expression for the inverse transform of

$$X(s) = \frac{1}{s} e^{-3s} F(s)$$

We notice this is of the form  $F(s)G(s)$  where  $G(s) = \frac{1}{s} e^{-3s}$

Oh, so  $g(t) = H(t-3)$ .

Now we use the convolution property

$$\mathcal{L}^{-1}[F(s)G(s)](t)$$

$$= \int_0^t f(\tau) g(t-\tau) d\tau$$

$$= \int_0^t f(\tau) \underbrace{H(t-\tau-3)}_{\text{rewrite very slightly as } H(t-3-\tau)} d\tau$$

if  $\tau < t-3$   
this is 1  
if  $\tau > t-3$   
this is 0

$$= \int_0^{t-3} f(\tau) d\tau$$

(provided  $t > 3$  -  
if  $t \leq 3$  this is  
just 0)